## Versatile and Powerful

- Minimum 160 in-lb torque in a compact package.

For damper areas up to $40 \mathrm{sq}-\mathrm{ft}^{\star}$.

## Areas of Application



Fits J ackshafts also.

## AM Series - at a glance

| Torque: 160 in-lb | - | - | $\bigcirc$ | $\bigcirc$ | 133in-lb |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Power supply: 24 VAC/DC | $\bigcirc$ | - | - | $\bigcirc$ | - |
| Control signal: on-off/floating | $\bigcirc$ | - |  |  | On/Off |
| Control signal: proportional 2 to 10 VDC |  |  | $\bigcirc$ |  |  |
| Control signal: $\quad 0 . . .135 \Omega$ or Honeywell ${ }^{\oplus}$ Electronic Series 90 |  |  |  |  |  |
| 0 to 20 V phasecut |  |  |  | $\bigcirc$ |  |
| Feedback: 2 to 10 VDC |  | - |  | - |  |
| Running time: 150 sec constant |  |  | $\bigcirc$ | $\bigcirc$ |  |
| Running time: $\begin{array}{ll}110 \text { to } 150 \mathrm{sec} \\ \text { load dependent }\end{array}$ | $\bigcirc$ | $\bigcirc$ |  |  |  |
| $\begin{array}{ll}\text { Running time: } & \begin{array}{ll}100 \text { to } 200 \mathrm{sec} \\ \text { load dependent }\end{array}\end{array}$ |  |  |  |  |  |
| $\begin{array}{ll}\text { Running time: } & \begin{array}{l}16 \text { to } 19 \mathrm{sec} \\ \\ \text { load dependent }\end{array}\end{array}$ |  |  |  |  | $\bigcirc$ |
| External direction of rotation switch | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ |
| Conduit fitting | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ |
| Appliance cable | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Built-in auxiliary switches |  | $\bigcirc$ |  |  |  |
| UL listed, CSA certified, CE | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |

Auxiliary switches and feedback potentiometer $\qquad$
Installation instructions
..(p. 91-95)
General wiring $\qquad$ (p. 93)

Start-up and checkout (p.96)

* $4 \mathrm{in}-\mathrm{lb} / \mathrm{ft}^{2}$ damper torque loading. Parallel blade. No edge seals.


## A CLOSER LOOK... <br> c <br>  <br> ISO 9001

- $20 \%$ more torque than SM .
- Fits inside 4" damper frame.
- Full stroke overload protection.
- Electronic deadband for accuracy and stability (proportional models).
- Easy direct coupled mounting, including jackshafts to 1.05 ".
- Check damper position with clear position indicator.
- Set actuator to compensate for damper seal wear and compression (proportional models).
- Constant running time aids control loop tuning (proportional models).
- Added flexibility with built-in mechanical stops.
- Fully adjustable, built-in auxiliary switches (AM24-S US only).
- Auxiliary switch add-on mounts on clamp, includes conduit fitting (SA1 US, SA2 US).
- Push button manual override
- Easily reverse control direction with switch on housing
- 3' cable speeds installations
- Micro processor controlled Brushless DC Motor


The Belimo Difference

- Customer Commitment.

Extensive product range. Competitive project pricing. Application assistance. Same-day shipments. Free technical support. Five year warranty.

## - Low Installation and Life-Cycle Cost.

Easy installation. Accuracy and repeatability.
Low power consumption. No maintenance.

## - Long Service Life.

Components tested before assembly. Every product tested before shipment.
$20+$ years direct coupled actuator design.


| Technical Data | AM24 US, AM24-S US |
| :---: | :---: |
| Power supply | $24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz} 24 \mathrm{VDC} \pm 10 \%$ |
| Power consumption | 2.5 W |
| Transformer sizing | 4.5 VA (Class 2 power source) |
| Electrical connection | $3 \mathrm{ft}, 18 \mathrm{GA}$, appliance cable, $1 / 2$ " conduit connector |
| Overload protection | electronic throughout 0 to $95^{\circ}$ rotation |
| Angle of rotation | 0-95 ${ }^{\circ}$ adjustable stops |
| Torque | min $160 \mathrm{in}-\mathrm{lb}$ [18 Nm] |
| Direction of rotation | reversible with switch "CCW-CW" |
| Position indication | clip-on indicator |
| Running time | 110 to 150 sec . for 0 to $160 \mathrm{in}-\mathrm{lb}$ |
| Manual override | external push button |
| Humidity | 5 to $95 \% \mathrm{RH}$, non-condensing |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $+122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.+50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $+176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.+80^{\circ} \mathrm{C}\right]$ |
| Housing type | NEMA 2 (IP54 with cable entry down) |
| Housing material rating | UL94-5V (flammability rating) |
| Noise level | less than $45 \mathrm{~dB}(\mathrm{~A})$ |
| Servicing | maintenance free |
| Agency listings | UL 873 listed, CSA C22.2 No. 24 cerrified, CE |
| Quality standard | ISO 9001 |
| Weight | 2.8 lbs [1.3 kg] |

## AM24-S US

Auxiliary switches adj. $0^{\circ}$ to $95^{\circ}, 2 \times$ SPDT $3 \mathrm{~A}(0.5 \mathrm{~A})$ @24 VAC

Torque min. 160 in -lb, for control of air dampers.

## AM24 US <br> AM24-S US

## Application

For on-off and floating point control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft up to $3 / 4$ " in diameter by means of its universal clamp, or up to a 1.05 " jackshaft with the optional K4-1 clamp. A crankarm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The angle of rotation is mechanically limited to $95^{\circ}$. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover. The position of the actuator is indicated by a visual pointer. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The AM24-S US version is provided with two built-in auxiliary switches. These SPDT switches are provided for safety interfacing or signaling. The switching function is adjustable between 0 and $95^{\circ}$.

Dimensions (All numbers in brackets are metric.)


## Accessories

AV 1
AV10-18
K4 US
K4-1 US
K4-H
KH-AM
SA1 US, SA2 US
PA... US
Tool-01
ZG-AM
ZG-100
ZG-101
ZG-103
ZG-104
ZS-100
ZS-150
Weather shield (polycarbonate)
ZS-260 Explosion-proof housing
ZS-300 NEMA 4X housing

## AM24 (-S) US - Typical Specification:

Control damper actuators shall be electronic direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05 " diameter. Actuators shall be UL and CSA listed, have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall have reversing switch and manual override on the cover, and be protected from overload at all angles of rotation. If required, two adjustable SPDT auxiliary switches shall be provided (AM24-S US). Actuators shall be as manufactured by Belimo.

## Wiring diagrams



On-off control


Floating point or on-off control


Auxiliary switch wiring for AM24-S US

## Notes



Provide overload protection and disconnect as required.
Actuators may also be powered by 24 VDC.
For end position indication, interlock control, fan startup, etc., AM24-S us incorporates two built-in auxiliary switches: $2 \times$ SPDT, 3A ( 0.5 A ) @24 VAC, UL listed, adjustable between $0^{\circ}$ and $95^{\circ}$.

Meets UL and CSA requirements without the need of an electrical ground connection.

Proportional damper actuator, non-spring return, direct coupled, 24 V , for $\mathbf{2}$ to 10 VDC and 4 to $\mathbf{2 0} \mathbf{~ m A ~ c o n t r o l ~ s i g n a l ~}$


| Technical Data | AM24-SR US |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \text { VAC, } \pm 20 \%, 50 / 60 \mathrm{~Hz} \\ & 24 \text { VDC, } \pm 10 \% \end{aligned}$ |
| Power consumption | 2.5 W running, 1.2 W holding |
| Transformer sizing | 5 VA (Class 2 power source) |
| Operating range Y | 2 to 10 VDC, 4 to 20 mA |
| Input impedance | $100 \mathrm{k} \Omega(0.1 \mathrm{~mA}), 500 \Omega$ for 4 to 20 mA |
| Feedback output 'U' | 2 to $10 \mathrm{VDC}, 0.5 \mathrm{~mA}$ max |
| Electrical connection | $3 \mathrm{ft}, 18 \mathrm{GA}$, appliance cable, $1 / 2$ " conduit connector |
| Overload protection | electronic throughout 0 to $95^{\circ}$ rotation |
| Torque | min 160 in-lb (18 Nm) |
| Direction of rotation | reversible with switch "CCW-CW" CW with a decrease in voltage CCW with a decrease in voltage |
| Position indication | clip on indicator |
| Manual override | external push button |
| Angle of rotation | 0-95 ${ }^{\circ}$ adjustable stops |
| Running time | 150 secs. constant, independent of load |
| Run time stability | $\pm 5 \%$ |
| Humidity | 5 to $95 \% \mathrm{RH}$, non-condensing |
| Operating temperature | -22 to $+122^{\circ} \mathrm{F}\left(-30\right.$ to $\left.+50^{\circ} \mathrm{C}\right)$ |
| Storage temperature | -40 to $+176^{\circ} \mathrm{F}\left(-40\right.$ to $\left.+80^{\circ} \mathrm{C}\right)$ |
| Housing | NEMA 2 (IP54 with cable entry down) |
| Housing material | UL 94-5V (flammability rating) |
| Noise level | less than 45 dB (A) |
| Agency listings | UL 873 listed, CSA C22.2 No. 24 certified, CE |
| Quality standard | ISO 9001 |
| Servicing | maintenance free |
| Weight | 2.8 lbs. (1.3kg.) |

Torque min. 160 in-lb, for control of air dampers.

## Application

For proportional modulation of dampers in HVAC systems. Actual actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft up to $3 / 4$ " in diameter by means of its universal clamp, or up to a 1.05 " jackshaft with the optional K4-1 clamp. A crankarm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.

## Operation

The actuator operates in response to a 2 to 10 VDC, or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication or master-slave applications.

The actuator has a constant running time of 150 seconds. A functional test of the actuator-damper assembly may be done by pressing in the manual override button, this will activate the actuators test mode and cycle the actuator fully closed and back to control point. The microprocessor will correct for compression of tight close-off gaskets with age, providing the actuator is not on its mechanical stops.

A 2 to 10 VDC feedback (U) is provided with full 8 volt output range proportional to the operational rotation of the damper. A digital rotation sensing circuit protects the actuator in a stall anywhere in its $95^{\circ}$ operating range without the need of limit switches. Add on auxiliary switches are easily fastened directly onto the actuator body for signalling and switching functions.

Dimensions (All numbers in brackets are metric.)


## Accessories

AV 1
AV10-18
K4-1 US
K4-H
KH-AM
SA1 US, SA2 US Auxiliary switches
PA... US $\quad 140 \Omega, 500 \Omega, 1000 \Omega, 2800 \Omega$ feedback potentiometers
PTA-250 Pulse width modulation interface
Tool-01 $\quad 10 \mathrm{~mm}$ wrench
SGA24 Min. and/or man. positioner in NEMA 4 housing
SGF24 Min. and/or man. positioner for flush panel mounting
ZAD24 Digital position indication
ZG-R01 $500 \Omega$ resistor for 0 to 20 mA control signal
ZG-AM Crank arm adaptor kit
ZG-100 Mounting bracket
ZG-101 Mounting bracket
ZG-103 Mounting bracket
ZG-104 Mounting bracket
ZS-100 Weather shield
ZS-150 Weather shield
ZS-260 Explosion-proof housing
ZS-300 NEMA 4X housing

## AM24-SR US - Typical Specification:

Control damper actuators shall be electronic direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05 " diameter.
Actuators shall be UL and CSA listed, have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. The actuator must provide proportional damper control in response to a 2 to 10 VDC, or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have reversing switch and gear disengagement button on the cover, and be electronically protected from overload at all angles of rotation. Actuators shall respond to 2 to 10VDC output relative to position regardless of the amount of damper rotation. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication or master-slave applications. Actuators shall be as manufactured by Belimo.

## Wiring diagrams



Proportional damper actuator, non-spring return, direct coupled, 24 V , for 0 to 20 V phasecut control signal


| Technical Data | AM24-PC US |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \text { VAC, } \pm 20 \%, 50 / 60 \mathrm{~Hz} \\ & 24 \text { VDC, } \pm 10 \% \end{aligned}$ |
| Power consumption | 2.5 W running, 1.2 W holding |
| Transformer sizing | 5 VA (Class 2 power source) |
| Operating range Y | 0 to 10 V , phasecut |
| Input impedance | $8 \mathrm{k} \Omega(50 \mathrm{~mW})$ |
| Feedback output 'U' | 2 to $10 \mathrm{VDC}, 0.5 \mathrm{~mA}$ max |
| Electrical connection | $3 \mathrm{ft}, 18 \mathrm{GA}$, appliance cable, $1 / 2^{\prime \prime}$ conduit connector |
| Overload protection | electronic throughout 0 to $95^{\circ}$ rotation |
| Torque | min $160 \mathrm{in}-\mathrm{lb}(18 \mathrm{Nm})$ |
| Direction of rotation | reversible with switch "CCW-CW" CW with a decrease in voltage CCW with a decrease in voltage |
| Position indication | clip on indicator |
| Manual override | external push button |
| Angle of rotation | 0-95 ${ }^{\circ}$ adjustable stops |
| Running time | 150 secs. constant, independent of load |
| Run time stability | $\pm 5 \%$ |
| Humidity | 5 to $95 \%$ RH, non-condensing |
| Operating temperature | -22 to $+122^{\circ} \mathrm{F}\left(-30\right.$ to $\left.+50^{\circ} \mathrm{C}\right)$ |
| Storage temperature | -40 to $+176^{\circ} \mathrm{F}\left(-40\right.$ to $\left.+80^{\circ} \mathrm{C}\right)$ |
| Housing | NEMA 2 (IP54 with cable entry down) |
| Housing material | UL 94-5V (flammability rating) |
| Noise level | less than 45 dB (A) |
| Agency listings | UL 873 listed, CSA C22.2 No. 24 certified, CE |
| Quality standard | ISO 9001 |
| Servicing | maintenance free |
| Weight | 2.8 lbs. (1.3kg.) |

Torque min. 160 in-lb, for control of air dampers.

## Application

For proportional modulation of dampers in HVAC systems. Actual actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft up to $3 / 4$ " in diameter by means of its universal clamp, or up to a 1.05 " jackshaft with the optional K4-1 clamp. A crankarm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.

## Operation

The actuator operates in response to 0 to 10 V phasecut control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication or master-slave applications.

The actuator has a constant running time of 150 seconds. A functional test of the actuator-damper assembly may be done by pressing in the manual override button, this will activate the actuators test mode and cycle the actuator fully closed and back to control point. The microprocessor will correct for compression of tight close-off gaskets with age, providing the actuator is not on its mechanical stops.

A 2 to 10 VDC feedback (U) is provided with full 8 volt output range proportional to the operational rotation of the damper. A digital rotation sensing circuit protects the actuator in a stall anywhere in its $95^{\circ}$ operating range without the need of limit switches. Add on auxiliary switches are easily fastened directly onto the actuator body for signalling and switching functions.

Dimensions (All numbers in brackets are metric.)


## Accessories

| AV 1 | Damper shaft extension for AM |
| :--- | :--- |
| AV10-18 | Universal shaft extension |
| K4-1 US | Clamp for 3/4" to $1.05 "$ jackshafts |
| K4-H | Hex shaft clamp, for $3 / 8 "-5 / 8 "$ shafts |
| KH-AM | Crankarm |
| SA1 US, SA2 US Auxiliary switches |  |
| PA... US | $140 \Omega, 500 \Omega, 1000 \Omega, 2800 \Omega$ feedback |
|  | potentiometers |
| PTA-250 | Pulse width modulation interface |
| Tool-01 | 10 mm wrench |
| SGA24 | Min. and/or man. positioner in NEMA 4 housing |
| SGF24 | Min. and/or man. positioner for flush panel mounting |
| ZAD24 | Digital position indication |
| ZG-R01 | $500 \Omega$ resistor for 0 to 20 mA control signal |
| ZG-AM | Crank arm adaptor kit |
| ZG-100 | Mounting bracket |
| ZG-101 | Mounting bracket |
| ZG-103 | Mounting bracket |
| ZG-104 | Mounting bracket |
| ZS-100 | Weather shield |
| ZS-150 | Weather shield |
| ZS-260 | Explosion-proof housing |
| ZS-300 | NEMA 4X housing |

## AM24-PC US - Typical Specification:

Control damper actuators shall be electronic direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter.
Actuators shall be UL and CSA listed, have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. The actuator must provide proportional damper control in response to a 0 to 10 V phasecut control input from an electronic controller or positioner. Actuators shall have reversing switch and gear disengagement button on the cover, and be electronically protected from overload at all angles of rotation. Actuators shall respond to 2 to 10VDC output relative to position regardless of the amount of damper rotation. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication or master-slave applications. Actuators shall be as manufactured by Belimo.

## Wiring diagrams




## Wiring diagram

## 24 VAC/VDC



For end position indication, interlock control, etc., SM24-S incorporates 2 built-in auxiliary switches $2 \times$ SPST (2A) 24 V UL listed

| Technical Data | SM24-S |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz} \\ & 24 \mathrm{VDC} \pm 10 \% \end{aligned}$ |
| Power consumption AC | Stand-by 1.2 W <br> Full Load 9.5 W |
| Transformer sizing | 12 VA |
| Electrical connection | $3 \mathrm{ft}, 18 \mathrm{GA}$ cable 1/2" conduit connector |
| Angle of rotation | mechanically limited to $95^{\circ}$ |
| Torque at rated voltage | 133 in-lb [15 Nm] |
| Direction of rotation | reversible with switch A / B ロ |
| Position indication | $0 \ldots 10$ and reversible indicator |
| Running time | Load Free approx. 16 seconds Full Load approx. 19 seconds |
| Auxiliary switch Open/Closed | 2 SPST 2A, 24 V |
| Humidity | 5 to 95\% RH non-condensing |
| Housing type | NEMA type 2 |
| Housing material rating | UL 94V-0 (flammability rating) |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $+122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.+50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $+176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.+80^{\circ} \mathrm{C}\right]$ |
| Noise level | 45 dB (A) |
| Servicing | maintenance free |
| Service life | minimum 10,000 operations |
| Weight | 3.3 lbs . [1.5 kg] |

Torque min. 133 in-lb, for control of damper surface up to $35 \mathrm{ft}^{2}$.

## Application

For on-off, fast-acting, control of dampers up to approximately $35 \mathrm{ft}^{2}$ [ $3 \mathrm{~m}^{2}$ ] (based on 4 in-lb per sq. ft.). Actual actuator sizing should be done in accordance with the damper manufacturer's specifications. Control is on-off, two position, from an auxiliary contactor or a manual switch. The direction of rotation is reversible by the use of a switch located on the actuator cover.

## Operation

The actuator is, by means of a special clamp, directly mounted onto the damper shaft.
The universal mounting bracket supplied with the actuator will prevent lateral movement of the actuator. The damper actuator is not provided with and does not require any limiting switches, but is protected against overloading.
The angle of rotation is mechanically limited to $95^{\circ}$. When reaching the damper or actuator end position, the motor stops automatically.
The gears can be manually disengaged by simply pressing down the spring loaded button on the actuator cover. When the button is pressed down, the damper blades can be adjusted by hand. The position of the actuator is indicated by means of a scale reading $0 . . .10$.
For end position indication, interlock control, etc., two built-in, non-adjustable auxiliary switches are provided with the actuator.

## Accessories

ZG-SM2 Crank arm adaptor kit ZDB Angle of rotation limiter
ZG-100 Universal mounting bracket
ZG-101 Universal mounting bracket
ZG-102 Multiple actuator mounting bracket
ZG-H2 Actuator operator handle
ZS-100 Weather shield, metal
ZG-150 Weather shield, polycarbonate

Dimensions (All numbers in brackets are metric.)


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| Technical Data | SA1 US SA2 US |
| :---: | :---: |
| No. of switches | 1xSPDT 2xSPDT |
| Switching capacity | 6 A (2.5A) 250 VAC |
| Switching point | adjustable over full actuator rotation 0 to 1 . Pre-setting with scale possible. |
| Electrical connection | $3 \mathrm{ft}, 18 \mathrm{GA}$ appliance cable 1/2" conduit connector |
| Humidity | 5 to 95\% RH non-condensing |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $+122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.+50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $+176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.+80^{\circ} \mathrm{C}\right]$ |
| Housing type | NEMA type 2 |
| Housing material rating | UL 94-5VA (flammability rating) |
| Agency listings | UL 873 listed, CSA C22.2 No. 24 cerrified, CE |
| Weight | $8 \mathrm{oz} \mathrm{[225} \mathrm{g]} 9.3 \mathrm{oz} \mathrm{[265} \mathrm{g]}$ |
| Electrical protection | auxiliary switches are double insulated |

## Mounting Instructions

1. Remove pointer assembly from the actuator. Press down the manual override button and rotate the actuator fully counter-clockwise.
2. Invert SA... US switch and turn the driver disk fully clockwise as indicated.
3. Slide SA... US switch onto actuator and check for the correct mating of the driver disk to the universal clamp. Secure with screw.
4. Adjust switch dials as necessary
5. Remount the white plastic pointer only onto SA... US switch.


## For the direct coupled actuator AM2...



## Wiring diagram



| Types |  |  |
| :--- | :--- | :--- |
| PA500 US | Feedback potentiometer | $500 \Omega$ |
| PA1000 US | Feedback potentiometer | $1000 \Omega$ |
| PA2800 US | Feedback potentiometer | $2800 \Omega$ |


| Technical Data | PA... US |
| :--- | :--- |
| Resistance values | as above |
| Output | 1 W |
| Tolerance | $\pm 5 \%$ |
| Linearity | $\pm 2 \%$ |
| Resolution | min. $1 \%$ |
| Residual resistance | max. $5 \%$ on both sides |
| Electrical connection | $3 \mathrm{ft}, 18 \mathrm{GA}$ appliance cable |
| $1 / 2^{\prime \prime}$ conduit connector |  |
| Humidity | 5 to $95 \%$ RH non-condensing |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $+122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.+50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $+176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.+80^{\circ} \mathrm{C}\right]$ |
| Housing | NEMA type 2 |
| Housing rating | $\mathrm{UL} 94-5 \mathrm{~V}$ (flammability rating) |
| Servicing | maintenance free |
| Agency listings | UL 873 listed, CSA C22.2 No.24 certified, CE |
| Quality standard | ISO 9001 |
| Weight | 8.8 oz $[250 \mathrm{~g}]$ |
| Electrical protection | Class 2 circuits |

## Application

The PA... US feedback potentiometers are used with AM actuators to provide a resistive signal which varies with damper position. The PA... US units are applied with commercial proportional temperature controllers to provide feedback of the damper position, or with electric or electronic meters to provide position indication. The signal can also be used as a positioner for parallel operation of multiple actuators.

## Operation

The PA... US feedback potentiometer is mounted onto the damper actuator. A driver disk is attached to the actuator clamp and offers direct transmission of the actuator to the potentiometer.

## Mounting Instructions

1. Remove pointer assembly from the actuator. Press down the manual override button and rotate the actuator fully counter-clockwise.
2. Invert PA... US and turn the driver disk fully clockwise as indicated.
3. Slide PA... US onto actuator and check for the correct mating of the driver disk to the universal clamp. Secure with screw.
4. Remount the white plastic pointer only, from the pointer assembly, onto PA... US.


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1. Turn damper blade to its fully closed position. With manual override button depressed, rotate actuator clamp to about $1 / 16$ " $-1 / 8^{\prime \prime}$ between actuator stop and clamp, depending on damper seal design. Slide actuator over shaft and fingertighten nuts.
2. Using a screwdriver, Select clockwise or counterclockwise rotation. (Example shown is for clockwise closing damper). Slide anti-rotation bracket up under actuator engaging center cut-out on actuator back. Secure bracket with self-tapping screws.

AM Series... Installation Instructions
Quick-Mount Visual Instructions

3. Tighten the two nuts on the universal clamp with 10 mm wrench, 6-8 ft-lb torque. (On dampers with edge seals, actuator will compress damper blades when reaching end position for air-tight damper.)
4. Adjust end stops, if required.

## Actuator sizing/preliminary steps

## Preliminary steps

1. Belimo actuators should be mounted indoors in dry, relatively clean environment free from corrosive fumes. If the actuator is to be mounted outdoors, a protective enclosure must be used to shield the actuator. (See Belimo Mechanical Accessories Doc. 5.2)
2. For new construction work, order dampers with extended shafts. Instruct the installing contractor to allow space for mounting and service of the Belimo actuator on the shaft.
3. The AM Series actuator requires a minimum shaft length of 1.88 ". Use the AV1 for short shaft installations on 1/2" diameter shafts.

## Replacement or mounting of optional mounting clamp

1. Squeeze tabs of retaining ring and lift off of actuator.
2. Remove clamp.
3. Replacement clamp has an alignment mark.

Match this mark with the similar mark on the actuator and mount clamp.
4. Squeeze tabs of retaining ring and fit it into the retaining slot.

Note: If retaining ring is not fully seated, the clamp may come loose from the actuator.


| AM actuators which may <br> be used on one shaft: |  |
| :--- | :---: |
| Model | Max <br> Quantity <br> Per Shaft |
| AM24 (-S) US | 4 |
| AM24-SR US | 4 |

WARNING The wiring technician must be trained and experienced with electronic circuits. Disconnect power supply before attempting any wiring connections or changes. Make all connections in accordance with wiring diagrams and follow all applicable local and national codes. Provide disconnect and overload protection as required. Use copper, twisted pair, conductors only. If using electrical conduit, the attachment to the actuator must be made with flexible conduit.

## Always read the controller manufacturer's installation literature carefully before making any connections. Follow all instructions in this literature. If you have any questions, contact

 the controller manufacturer and/or Belimo.
## Transformer(s)

The AM Series actuators require a 24 VAC class 2 transformer and draw a maximum of 5 VA . The actuator enclosure cannot be opened in the field, there are no parts or components to be replaced or repaired.

- EMC directive: 89/336/EEC
- Software class A: Mode of operation type 1
- Low voltage directive: 73/23/EEC

CAUTION: It is good practice to power electronic or digital controllers from a separate power transformer than that used for actuators or other end devices. The power supply design in our actuators and other end devices use half wave rectification. Some controllers use full wave rectification. When these two different types of power supplies are connected to the same power transformer and the DC commons are connected together, a short circuit is created across one of the diodes in the full wave power supply, damaging the controller. Only use a single power transformer to power the controller and actuator if you know the controller power supply uses half wave rectification.

## Multiple actuators, one transformer

Multiple actuators may be powered from one transformer provided the following rules are followed:

1. The TOTAL current draw of the actuators (VA rating) is less than or equal to the rating of the transformer.
2. Polarity on the secondary of the transformer is strictly followed. This means that all No. 1 wires from all actuators are connected to the common leg on the transformer and all No 2 wires from all actuators are connected to the hotleg. Mixing wire No. 1 \& 2 on one leg of the transformer will result in erratic operation or failure of the actuator and or controls.

## Multiple actuators, multiple transformers

Multiple actuators positioned by the same control signal may be powered from multiple transformers provided the following rules are followed:

1. The transformers are properly sized.
2. All No. 1 wires from all actuators are tied together and tied to the negative leg of the control signal. See wiring diagram.

## Wire length for AM Series actuators

Keep power wire runs below the limits listed in the Fig. 1. If more than one actuator is powered from the same wire run, divide the allowable wire length by the number of actuators to determine the maximum run to any single actuator.

## Maximum wire length:

| Wire Size | Max. Feet. | Wire Size | Max. Feet |
| :---: | :---: | :---: | :---: |
| 12 Ga | 1800 Ft. | 18 Ga | 450 Ft. |
| 14 Ga | 1100 Ft. | 20 Ga | 275 Ft |
| 16 Ga | 700 Ft. | 22 Ga | 125 Ft |

Fig. 1
Example for AM... US: 3 actuators, 18 Ga wire $450 \mathrm{Ft} \div 3$ Actuators $=150 \mathrm{Ft}$. Maximum wire run.

## Wire Type and Wire Installation Tips

For most installations, 18 or 16 Ga . cable works well with the AM24 type actuators. Use code approved wire nuts, terminal strips or solderless connectors where wires are joined. It is good practice to run control wires unspliced from the actuator to the controller. If splices are unavoidable, make sure the splice can be reached for possible maintenance. Tape and/or wire tie the splice to reduce the possibility of the splice being inadvertently pulled apart.

## Overload protection

All Belimo actuators are electronically protected against overload. In the AM series an electronic circuit maintains the current at a level which will not damage the motor while providing adequate holding torque.

## Operational Information for AM Series Proportional Actuators

## Initialization

The proportional models of the AM series (AM24-SR US,) must go through an initialization procedure to learn the zero signal position. When the power is first applied to the actuator, or the gear release button is depressed, the actuator will move to its zero signal position. After the actuator learns this, it will drive to its control position.

Note: If power is lost to the actuator, and the actuator is moved by use of its manual override, the actuator must be re-initialized when power is returned, by pushing the override button.

## (AM24-SR US)

## Motor position detection

Belimo brushless DC motors eliminate the need for potentiometers for positioning. Inside the motor are three "Hall Effect" sensors. These sensors detect the spinning rotor and send pulses to the microprocessor which counts the pulses and calculates the position to within $1 / 3$ of a revolution of the motor.

## Installation Instructions

Feature operation

## Manual Override

A button on the actuator cover disengages the gear train so the damper shaft can be moved manually. Release the button and the gear train is re-engaged.

Use the manual override to test the installation without power. For tight shut-off the damper should close with $5^{\circ}$ of actuator stroke left.

Gear release button


## Direction of Rotation Switch

AM actuators have a reversing switch on the cover labeled "CW-CCW". Switch position indicates start point. For the AM24-SR US, with the switch in position "CW", the actuator rotates clockwise with an decrease in voltage or current. With the switch in position "CCW", the actuator rotates counterclockwise with an decrease in voltage or current.

The AM24 (-S) US rotates clockwise when the switch is in the "CW" position and power is applied to wire \#2. When power is applied to wire \#3 the actuator rotates counter clockwise.
Rotating the "CW/CCW" switch to "CCW" reverses the control logic.

During checkout, the switch position can be temporarily reversed and the actuator will reverse its direction. This allows the technician a fast and easy way to check the actuator operation without having to switch wires or change settings on the thermostat. When the check-out is complete, make sure the switch is placed back to its original position.


## Mechanical Angle of Rotation Limiting

The adjustable stops are needed when there is no damper stop or if you want the damper to stop rotating before it reaches its stops. The AM actuator can be indefinitely stalled in any position without harm.

1. Loosen the two end stops with a No. 2 Phillips head screwdriver being careful not to unscrew the captive nut under the slot.
2. Move the stops (in $2.5^{\circ}$ steps) to the desired position and retighten the screws.


## Control Accuracy and Stability

AM Series proportional actuators have built-in brushless DC motors which provide better accuracy and longer service life.
The AM Series actuators are designed with a unique non-symmetrical deadband. The actuator follows an increasing or decreasing control signal with a 80 mV resolution. If the signal changes in the opposite direction, the actuator will not respond until the control signal changes by 200 mV . This allows these actuators to track even the slightest deviation very accurately, yet allowing the actuator to "wait" for a much larger change in control signal due to control signal instability.

## AM Actuator responds to a 80 mV signal when not changing direction from stop position.



AM Actuator responds to a 200 mV signal when reversing direction from stop position.


## Adjustable Auxiliary Switches

The AM24-S US actuator is equipped with two adjustable auxiliary switches used to indicate damper position or to interface additional controls or equipment. Switching positions can be set over the full scale of 0 to $95^{\circ}$ simply by setting switch on the actuator cover.

## Method A

1. Push the manual override button and rotate the clamp to the " 0 " position.
2. Set the desired switch position: example: $20 \%$ of rotation is ".2" on the setting scale.
3. Check the switch operation. As the indicator passes the " 0 " switch position, the contact between S1 and S2, or S4 and S 5 , is broken and the contact between S1 and S3, or S5 and S 6 is made.
Switch Rating

| Voltage | Resistive load | Inductive load |
| :---: | :---: | :---: |
| 24 VAC | 3 A | 0.5 A |

## Accessories

## Mounting brackets

ZG-100 Mounting bracket
ZG-101 Mounting bracket
ZG-103 Mounting bracket
ZG-104 Mounting bracket

## Method B

1. Use manual override to position universal clamp to desired switch position.
2. Turn switch pointer to " 0 ".
(switch function may also be monitored by a meter for precise setting)


## ZG-AM - Crank arm adaptor kit



SA...us Auxiliary switches, PA...us Feedback potentiometers


## SGA24/SGF24

Minimum and/or manual positioner (electronic), SGA24 is enclosed in a NEMA 4 housing. The SGF24 is for flush panel mounting.


AM24SR US Electrical check-out procedure

| Step | Procedure | Expected Response | Gives Expected Response Go To Step... | Does Not Give Expected Response Go To Step... |
| :---: | :---: | :---: | :---: | :---: |
| 1. | Control signal is applied to actuator. | Actuator will move to its "Control Signal" position. | Actuator operates properly Step 9 | No response at all Step 2 <br> Operation is reversed Step 3 <br> Does not drive toward "Control Signal Position" Step 4 |
| 2. | Check power wiring. Correct any problems. See Note 1. | Power supply rating should be $\geq$ the total power requirement of the actuator(s). Minimum voltage of 19.2 VAC or 21.6 VDC. | Power wiring corrected, actuator begins to drive Step 1 | Power wiring corrected, actuator still does not drive Step 4 |
| 3. | Turn reversing switch to the correct position. | Actuator will move to its "Control Signal" position. | Actuator operates properly. Step 9 | Does not drive toward "Control Signal Position" Step 4 |
| 4. | Push manual override button. (If clamp is at min signal position, move damper to fully closed position) | Actuator will drive to 0 position and back to control position | Actuator operates properly. Step 9 | Step 5 |
| 5. | Make sure the control signal positive (+) is connected to Wire No 3 and control signal negative (-) is connected to wire No. 1. Most control problems are caused by reversing these two wires. Verify that the reversing switch is all the way CCW or CW. | Drives to "Control Signal" position | Actuator operates properly. Step 9 | Step 6 |
| 6. | Check input signal with a digital volt meter (DVM). Make sure the input is within the range of the actuator. For AM24SR US this is 0 to 10 VDC or 0 to 20 mA . <br> Note: The input signal must be above the 2 VDC or 4 mA to have the actuator move. | Input voltage or current should be $\pm 1 \%$ of what controller's adjustment or programming indicate. | Controller output (actuator input) is correct. Input Polarity Correct. Step 7 | Reprogram, adjust repair or replace controller as needed. Step 1 |
| 7. | Use the manual override button to move the damper by hand from fully closed to fully open. | Damper will go from fully closed to fully open. | Damper moves properly Step 8 | Find cause of damper jam and repair. Step 1 |
| 8. | Check damper torque requirement. | Torque requirement is $\leq$ actuator's minimum torque. | Defective Actuator. Replace Actuator See Note 2 | Recalculate actuator requirement and correct installation. |
| 9. | Actuator works properly. Test controller by following controller manufacturer's instructions. |  |  |  |

Note 1 Check that the transformer(s) are sized properly.

- If a common transformer is used, make sure that polarity is observed on the secondary. This means connect all No. 1 wires to one leg of the transformer and all No. 2 wires to the other leg of the transformer.
- If multiple transformers are used with one control signal, make sure all No. 1 wires are tied together and tied to control signal negative (-).
- Controllers and actuators must have separate 24 VAC/VDC power sources.

Note 2 If failure occurs within 5 years from original installation date, notify Belimo and give details of the application.

